



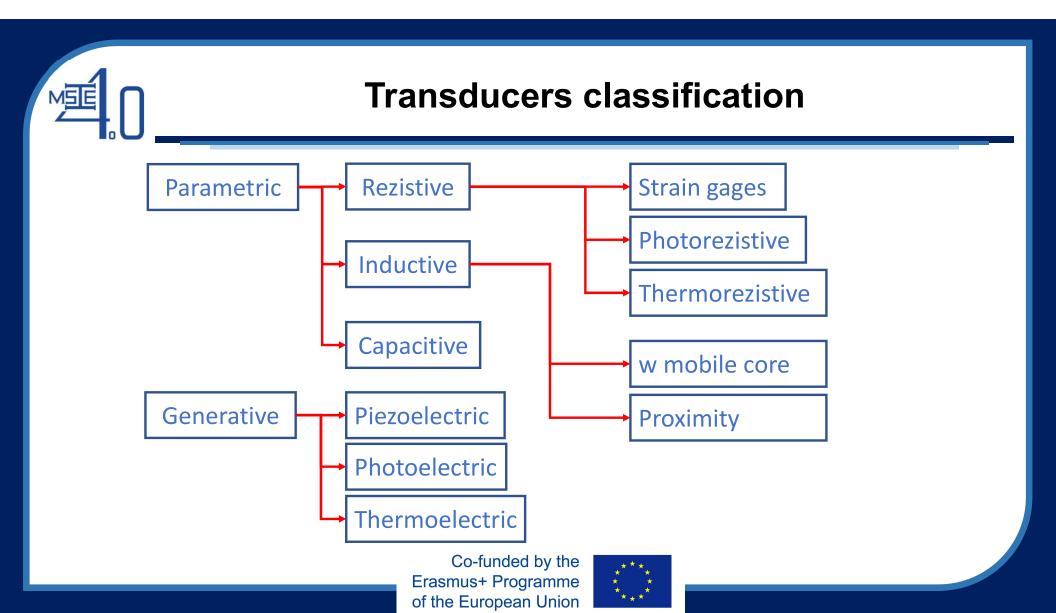
# Cyber-Physical Industrial Systems

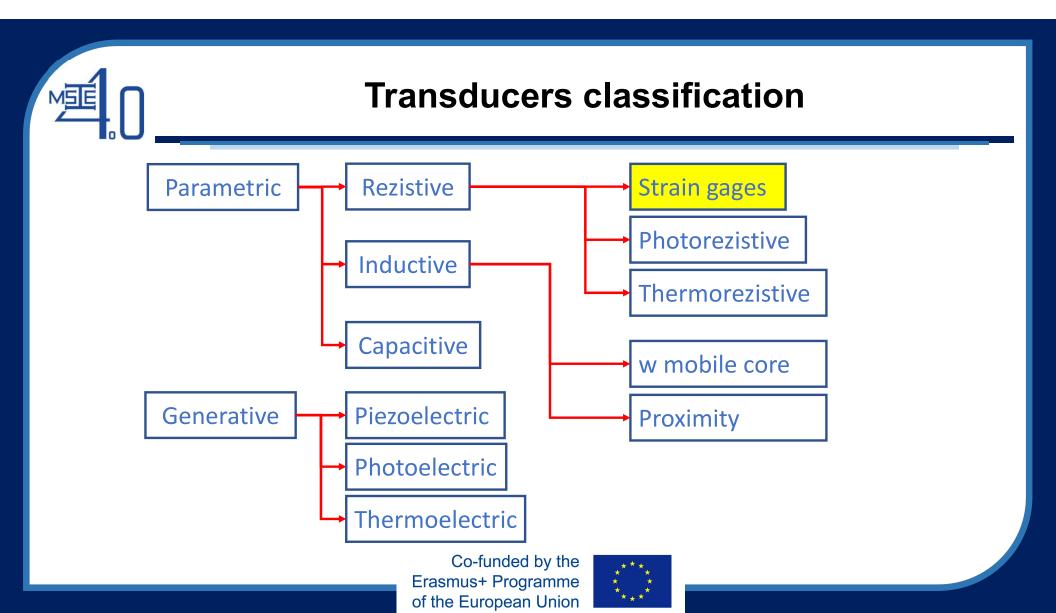
Module 1 Session 2

**Types of transducers** 

Lecture









# **Straing gages: characteristics**

$$R = \frac{\rho \cdot I}{S}$$

HB M

Working temperature

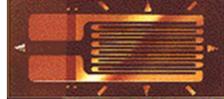
Working environment

**Grid** material

Support material

Adhesive

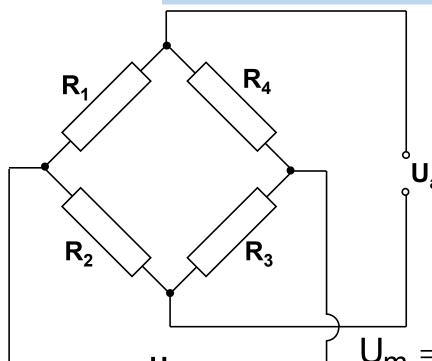








## Straing gages: Wheatstone bridge



$$R_i = 120 \Omega$$

$$U_a \in \{1, 2, 4, 8\}V$$

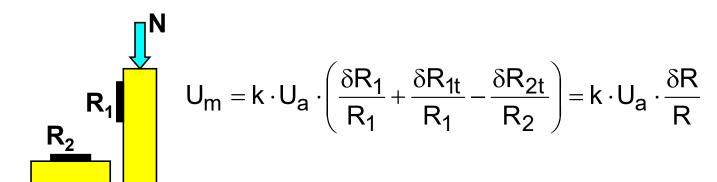
$$U_m \in [-10, 10]V$$

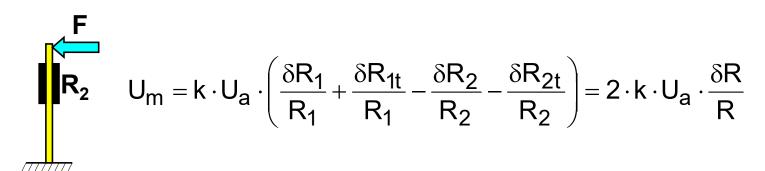
$$\overline{U_{m}} = k \cdot U_{a} \cdot \left( \frac{\delta R_{1}}{R_{1}} - \frac{\delta R_{2}}{R_{2}} + \frac{\delta R_{3}}{R_{3}} - \frac{\delta R_{4}}{R_{4}} \right)$$





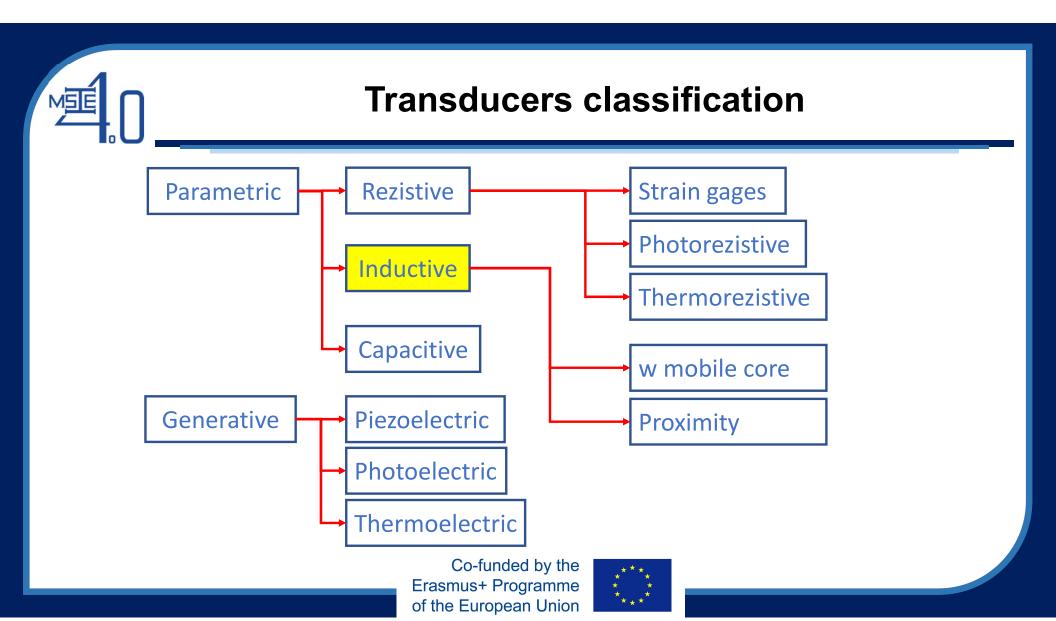
# Straing gages: compensating temperature effects









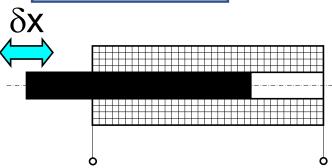




## **Inductive transducers**

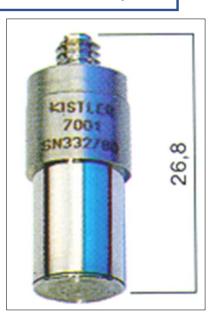




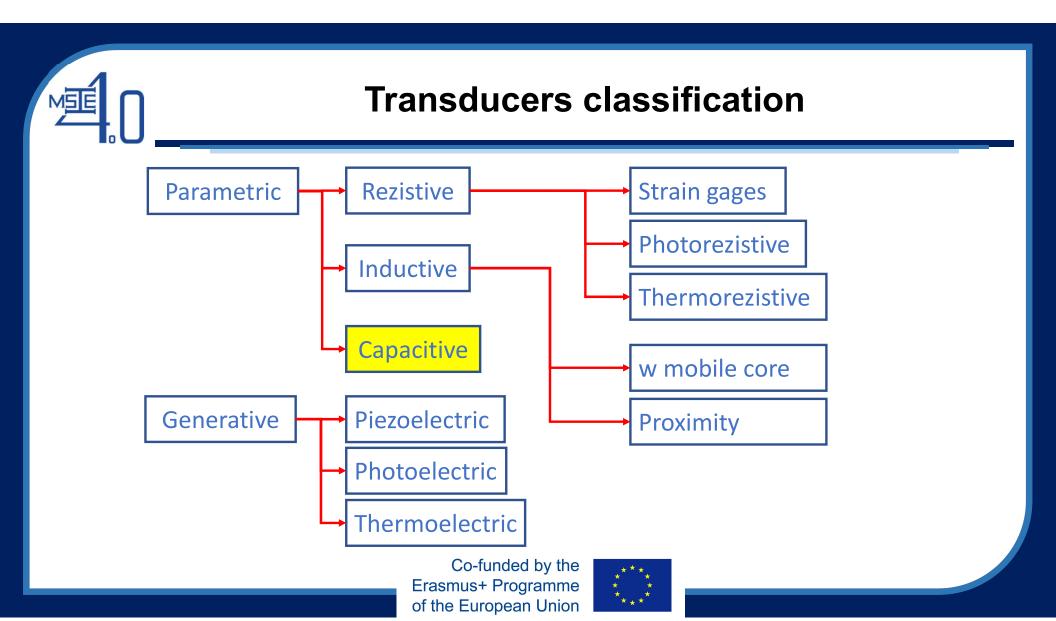


# Co-funded by the Erasmus+ Programme of the European Union

#### **Proximity**

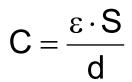


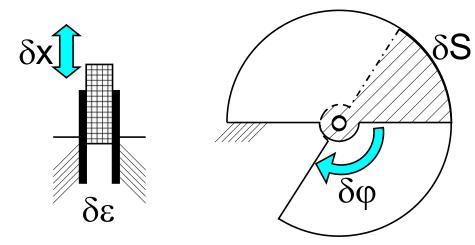


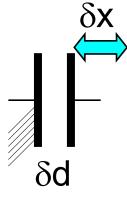


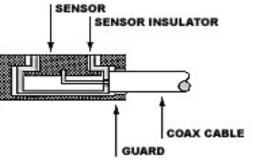


# **Capacitive transducers**

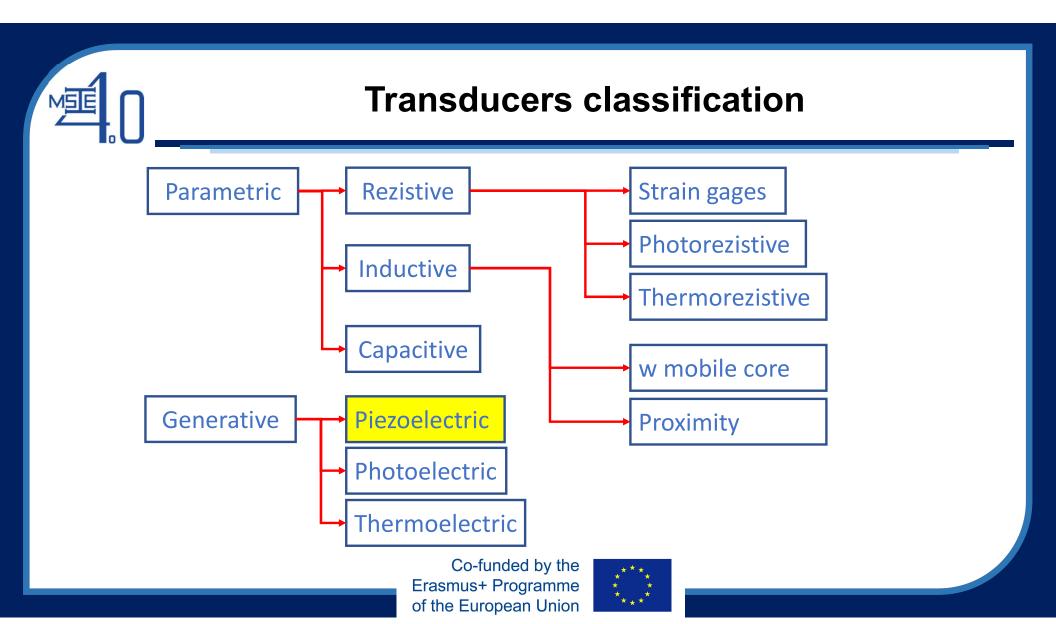






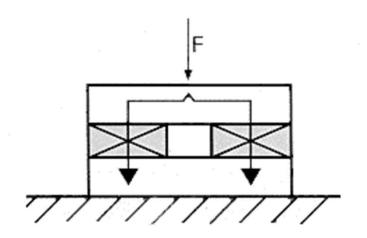


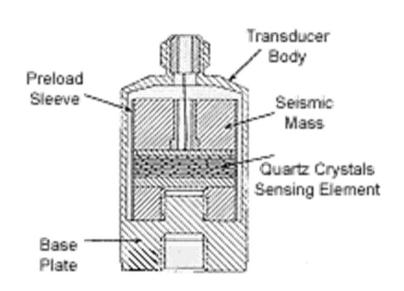




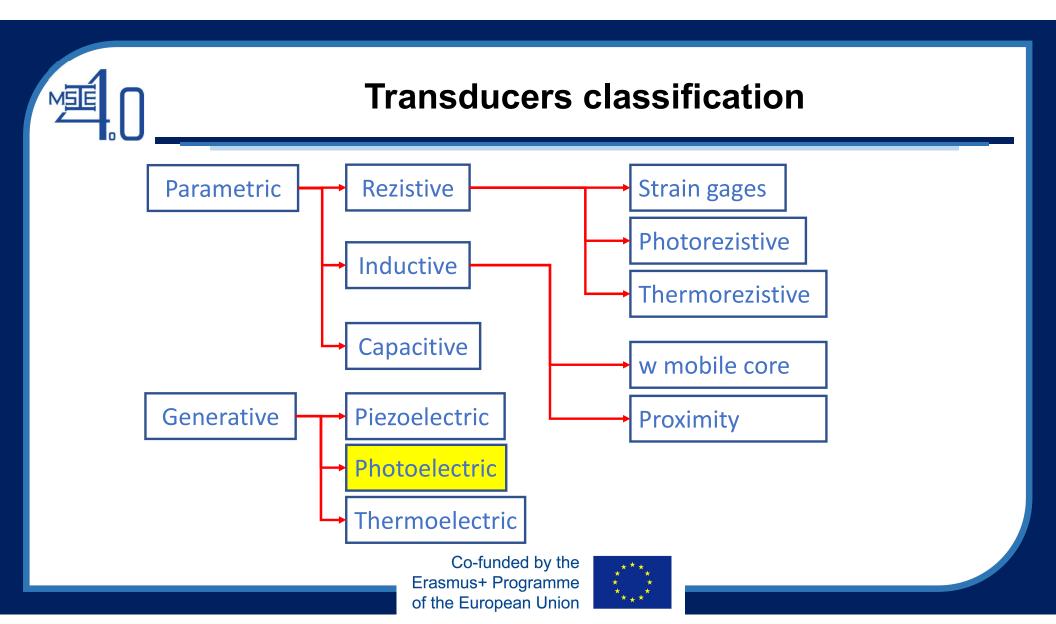


## Piezoelectric transducers



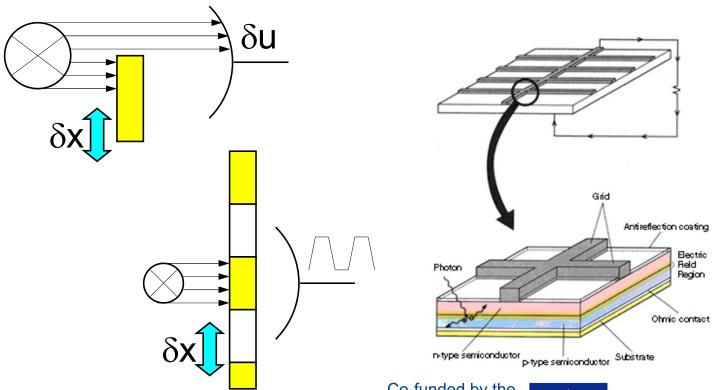


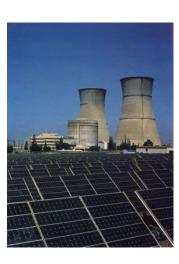




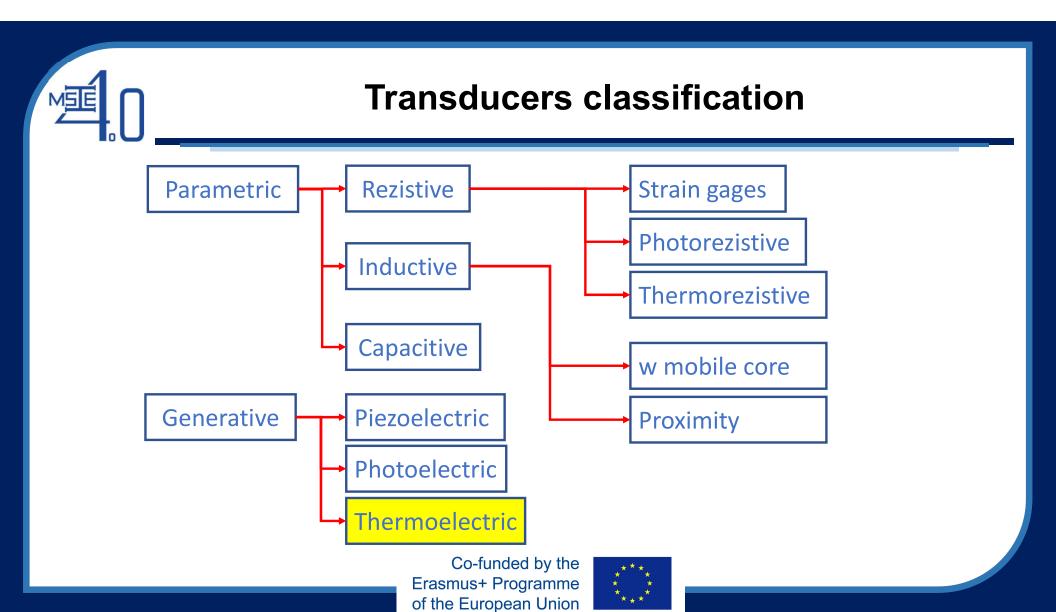


## **Photoelectric transducers**











### Thermoelectric transducers

