



Learning Outcome

Propose a digital factory platform of a case study factory in a virtual environment upon what have been learned (Design, Module III)



Content

Case study in industrial

- Production line balancing
- Production bottlenecks
- Production and logistics processes
- Production scenarios
- □ Aircraft engine parts
- □ Tire Automotive
- Automated guided vehicles
- □ Human and Robot operation
- □ Human–robot collaboration (HRC)
- **General Ergonomics in Practice**
- Digital Mock-Up for Mechanical products
- □ Spacecraft Collaborative Design Technology





Concept of Digital Manufacturing

The digital manufacturing can be used in the following areas

Manufacturing Planning

- 1. Define High-Level Manufacturing Processes
- 2. Process Planning (Assembly & Installation)
- 3. Define Work Instructions & Work Flow
- 4. Detailed Process Design & Analysis

Detailed Resource Modelling & Simulation

- 1. Process Definition and Validation
- 2. 3-D Factory Layout
- 3. Equipment, Tool & Fixture Simulation
- 4. Ergonomic Simulation

Validation & Virtual Commissioning

- 1. Control Logic Validation
- 2. Kinematic (Robotic) Validation
- 3. Quality Assurance/Process Improvement Validation
- 4. Sensor/Metrology Placement Validation
- 5. Virtual Commissioning/Validation of Automation Systems

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6. Knowing that the Production System Works Prior to Launch: Priceless.







Production line balancing

Simulation model of the balanced production lines

- bottlenecks appear the forklifts transportation and intervals of raw material entering on both lines.
- The forklift is just not able to transport all of the new component parts from the 1st and the 2nd line to the assembly workplace.

Improvement

- By entering one additional forklift to each production line the first bottleneck can be removed.
- By adjusting the interval of raw material entering into the each production line the second bottleneck can be removed.





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Zupan, 2015



Production line balancing

Final results of the simulation model

The overview over the utilization time of machines in the both production lines where the state before and after the line balancing is presented.



- After the execution of line balancing the production lines are aligned in a way that almost no operation ever waits to the components from a previous operation.
- The cycle time of the production is reduced nearly four times and the cycle time is now closer to assembly time.

Zupan, 2015

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waiting time is reduce.



Production line balancing

Critical points identification	Bottlenecks appear – the forklifts transportation and intervals of raw material entering on both lines. The forklift is just not able to transport all of the new component parts from the 1st and the 2nd line to the assembly workplace.
Indicator	State of buffers, utilization time of machines.
Improvement	By entering one additional forklift to each production line the first bottleneck can be removed and adjusting the interval of raw material entering into the each production line the second bottleneck can be removed.
Result	No operation ever waits. The cycle time of the production is reduced.



Zupan, 2015



Production bottlenecks

- The article presents the analysis and assessment of the chosen production line in two versions. The studies facilitated an initial evaluation of the efficiency of specific elements in the process and the indication of its bottleneck.
- Simulation models allow evaluating different variants of production and their effectiveness. In addition, the simulation allows to use new strategies and procedures, verification of the production in the revised system, locate bottlenecks in the flow of materials, increase productivity while reducing inventory and reduce the cost of the implemented changes.



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Kikolski, 2016



Production bottlenecks

Detailed statistics in the basic model

WORKPLACE	WORKING TIME [%]	Waiting time [%]	BLOCKED TIME [%]	Paused TIME [%]
M1	88.75		5.00	6.25
M2	38.29	0.18	55.28	6.25
M3	93.58	0.17	5 3	6.25
M4	61.22	32.53	-	6.25

Detailed statistics in extended model

WORKPLACE	WORKING TIME (PERCENTAGE)	WAITING TIME (PERCENTAGE)	BLOCKED TIME (PERCENTAGE)	PAUSED TIME (PERCENTAGE)
M1	93.75%		_	6.25%
M2	76.58%	5.59%	11.58%	6.25%
M3a	93.58%	0.17%		6.25%
M3b	93.49%	0.26%	-	6.25%
M4	61.22%	32.53%		6.25%

The introduced changes did not fully solve the problem of the bottleneck at the station M3, but they considerably improved the smooth operation of the entire production line.





Production bottlenecks

Critical points identification	M3 is the bottleneck of the analysed process. The station M3 causes considerable standstills at the station M2. The waiting time for semi-finished products at the station M4.
Indicator	Resource statistics, working time, waiting time, blocked time, paused time.
Improvement	Expand parallel station of the work node M3, which is the bottleneck of the output process.
Result	Increase the production capacity of the process and the vast reduction of the time of locking at the station M2 and expectations for components at the station M4. The analysed production line began to work smoothly.



Nails production

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simulate discrete events and create digital models of logistic systems (e.g. production), optimize the operation of production plants, production lines, as well as individual logistics processes.





Adding another, parallel workstation for sharpening the cut nails. Settings of the extra machine are the same as of the main one.



The wire cutting machine capacity was used only 10%. This station is blocked by the "Tip" machine, which is the bottleneck in this process.

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The wire cutting machine is working all the time now and 100% of its' capacity was actually used. This machine is not blocked by the "Tip" workstation any more.

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Siderska, 2016



Critical points identification	Optimize the operation of production plants, production lines, as well as individual logistics processes. This station is blocked by machine, which is the bottleneck in this process.
Indicator	Resource Statistics.
Improvement	Adding another, parallel workstation for sharpening the cut nails.
Result	The wire cutting machine is working all the time now and 100% of its' capacity was actually used. This machine is not blocked by the "Tip" workstation any more. The effect of shortening the time of assembly of one box from 60 to 30 seconds was also analyzed. This would make it possible to increase the production capacity even up to 1,726 pieces within 24 hours.

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Siderska, 2016



Production scenarios

Presents possibilities of applying computer simulation models in studying chosen production scenarios.



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Production scenarios



- The simulation period assumed one 8-hour shift.
- The simulation analysis leads to the conclusion that the highest efficiency was reached within the system providing elements in 15-item batches.
- It appeared that increasing batches of entered components lowered production efficiency.

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Kikolski, 2017



Production scenarios

Critical points identification	Reduce the volume of stocks while ensuring the continuity of the production process.	
Indicator	Resource Statistics, number of final products.	
Improvement	The scenario analysis for number of items of each component into the system. Finally, chosen the best production scenarios is maximum final products .	
Result	Reducing the batches entered into the system can increase its efficiency and flow of the transfers.	

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Aircraft engine parts

Two case studies industrial scenarios, i.e. mass and small batch production, are simulated with the aim of improving specified performance measures related to manufacturing cells productivity, such as throughput or throughput time, and utilization of resources.

Small batch in aerospace sector

Simulation models with the aim to analyse and possibly enhance the resources utilization and the batch throughput time, i.e. the time required to produce a whole batch of components.

Deburring or polishing, can often determine worker's injuries that could be avoided by introducing a higher level of automation based on devices such as robots.



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Caggiano, 2013



To reduce these risks and improve the manufacturing cell performance, a reconfigured manufacturing cell having an automated deburring cell provided with an industrial robot has been designed.



Layout of the reconfigured manufacturing cell

The 3D Motion Simulation model of the reconfigured manufacturing cell, including the machine tool, the Coordinate Measuring Machine (CMM) and the automated deburring cell.





Critical points identification	Deburring operations are performed manually by a human operator following a procedure that requires large experience, manual ability and mind concentration. An inaccurate operation or human inattention can produce severe damages to the processed component.	
Indicator	Utilization of the manufacturing cell resources.	
Improvement	Deburring or polishing, can often determine worker's injuries that could be avoided by introducing a higher level of automation based on devices such as robots.	
Result	Increase the throughput of the manufacturing cell by including external part numbers and to augment the utilization of the deburring cell from 9% to 44%.	

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Caggiano, 2013

Mass Production

Improve the efficiency of manufacturing cell by achieving the desired throughput level, expressed. In order to analyse the behaviour of the manufacturing cell and investigate how to achieve

A first simulation run is performed to obtain numerical results on current manufacturing cell throughput and utilization of resources, and to carry out bottlenecks analysis to identify the critical components.

Each one of these elements is characterised by two main parameters: **process cycle time** and **machine availability.**



Layout of the manufacturing cell DES model (Tecnomatix)

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Caggiano, 2013 🌈



6 parameters (process time and machine availability for each of the three machine tools). identified by the algorithm gives new results in terms of throughput (increased about 4%) and utilization of resources

The new simulation model set up with the values of the

 A multi-level experimental design with different combinations of the 6 previously defined parameters would require a very large number of experiments.

Layout of the manufacturing cell DES model (QUEST)

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Critical points identification	Improve the efficiency of manufacturing cell by achieving the desired throughput level, expressed as the number of produced units/day, giving information on the rate at which work can be handled by the system.	
Indicator	Cycle time and machine availability.	
Improvement	Set up with the values of the 6 parameters: process time and machine availability for each of the three machine tools.	
Result	New results in terms of throughput (increased about 4%) and reduce utilization of resources.	







Methodology for evaluation of best manufacturing practices [Molina and Medina 2000]. Accordingly, the activities done at each action-research cycle become as follows:

- **Plan:** (1) define problem and target according to the set of enterprise planning activities, (2) establish a set of objectives (3) specify the decision criteria for analyzing the alternatives (objective measures), and (4) propose one or more alternatives of the manufacturing system.
- Act: (1) Determine the type of model according to a model typology, (2) Develop a model and validate it.
- Carry experimentation if necessary.
- **Observe:** (1) simulate the model and (2) evaluate the objective measures.
- Reflect: (1) Identify one or more courses of action according to the results of the observe step and restart the cycle if necessary.

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Chavarria , 2018

AUTOMOTIVE SUPPLIER CASE STUDY

The manufacturing system is being designed to achieve the capacity of up to 500,000 parts per year.

Example 1: worker strategy

- Determine the best operator loading and unloading strategies for a group of six CNC machines, where two operators load and unload parts.
- One operator is responsible for loading and unloading material of three machines.

The distance travelled by the operators in the corridors and the distance between machines were obtained from the layout.

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Operation Model for loading and unloading materials in numeric control machines.





AUTOMOTIVE SUPPLIER CASE STUDY

Example 2: Optimal number of pallets



Integrated Model for two automated operations.

- Material handling in the new plant will be carried out by operators and through an automatic conveyor system.
- The system is composed of two workstations each having an automatic conveyor.
- An operator transfers each pallet from workstation WS1 to workstation WS2.
- The objective is to calculate a number of pallets in each workstation.
- The objective measure is to maximize the productivity in terms of number of parts produced per week.

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Chavarria , 2018

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Critical points identification	Generate the technology viewpoint from the Sensing, Smart and Sustainable Enterprise Reference Model (S3E-RM) which allows the integrated manufacturing enterprise design. Enhance the plant design process by generating accurate predictions allowing the evaluation of different alternatives.	
Indicator	Productivity, Optimal number of pallets.	
Improvement	Worker strategy and optimal number of pallets.	
Result	Worker strategyThe best strategy is strategy 3. The data obtained from the actual plant will be used as to adjust the model and make improvements if necessary.Number of pallet Compared to the initial estimate, the optimal number of pallets represents an increment of 40 additional parts per week.	
	Co-funded by the Chavarria , 2018 29/	

of the European Union





Automated guided vehicles

□ Introduces the method of the determination of number of automated guided vehicles and choosing of optimal internal company logistics track.

 The internal logistics in the factory, which aims into production volume growth. Such changes will require a new internal logistics routes.

Static calculation of vehicles number and data collection

- The calculation has to be done before the data collection.
- The company was operated in a three-shift operation mode, where expected disposable working time of vehicle per shift is 7,5 hour. Vehicles will recharge at fast charging station during worker's half hour break.
- Another data that need to be calculated are speed parameters of vehicles and loading and unloading time.



Automated guided vehicles

Two adjustments of **speed parameters** were carried out as follows:

- The vehicle's speed was *decreased* on 1 m/ per second on straight and 0,6 meter/ per second on the curve
- The vehicle's speed was *increased* on 2 m/ per second on straight and 1,6 meter/ per second on the curve

Development count of vehicles on specific system settings

for actual state of production

for **future state** of production (increase up to 66 pieces.)





Automated guided vehicles

Critical points identification	Production volume growth.
Indicator	Performance parameters and waiting time of vehicles.
Improvement	Introduces the method of the determination of number of automated guided vehicles and choosing of optimal internal company logistics track. A new internal logistics routes.
Result	The simulation results of the logistics system were variants for increasing the use of the operation areas, optimized material supply and created layout that would be able to flexibly response to the future company requirements.





Human and Robot operation

- □ This article is showing some basic processes of the simulation, which are human operation and robot operation.
- Create a 3D model of a human and place it to the workplace.

Hu	man <u>T</u> ools <u>H</u> elp	
1	Create Human	Create Human
(A)	Create Hands Change Human Model Properties	Create from library
÷Ŕ	Default Posture Human Postures	v7.0 Male v7.0 Male
新水	Reach Object Place Object Walk Creator Elevation Transition	Appearance: V70 Clothed Gender: Male Database: ANSUR.
	Envelopes •	Height (mm): 50% - 1750 -
-	Ergonomics) Time Assessment / Vision Window	Waist To Hip Ratio
	Additional Tools	OK Cancel
	Human Options	



The new human pose will be created and saved with the selected positions of human model.

Human creation in Process Simulate Co-funded by the Erasmus+ Programme of the European Union



Trebuna, 2014





Human and Robot operation

Creation of the robot operation

The new robot operation begins selecting the desired robot model.



Creation of robot operation

Then we need to create requested movements of the robot using Path Editor to adjust the partial positions of the robot and the time which is needed to reach these locations.







Human–robot collaboration (HRC): Assembly systems

- Besides the significance of assembly work in manufacturing, the application of collaborative robots in variety-oriented assembly systems is very limited.
- The issues solved by presented digital twins for HRC assembly are:
- Rapid skills-based workload balancing between human and robot for product variety;
- Dynamic workload balancing during operation to account for human factors;
- Trajectory planning and generating robot control program.

Digital twins in HRC assembly





Human–robot collaboration (HRC): Assembly systems

Critical points identification	Safety of humans and frequent reconfigurations in the assembly work.
Indicator	Sufficient synchronization possibilities between physical and digital spaces and high-fidelity simulation models.
Improvement	A 3-dimensional virtual simulation model of human–robot cooperation.
Result	The ease of automation and availability of the resource, the tasks are assigned to the appropriate resource.
	Frequent occurring human-positions are integrated with the simulation model to form an obstacle-envelope to optimize the robot trajectories.
	The approach supports the notion of automation while maintaining assembly flexibility.

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Bilberg, 2019



Ergonomics in Practice

Evaluated with the help of digital human models by means of two software (Tecnomatix Jack and Delmia) packages and theirs ergonomic analysis.

• Evaluation of existing workplaces at a specific workplace – sewing seat belts

These conditions are:

a) Software is able to represent investigated workplaces completely identically.b) Same size and proportions of digital human models.

c) Analyses must work on same principle,same calculation or same standards.d) Analyses have the same options.



Tecnomatix Jack and Delmia V5 Human workplace models

Co-funded by the Erasmus+ Programme of the European Union



Polášek, 2014





Ergonomics in Practice

Critical points identification	Prevent increased absence at work due to health problems, excessive employee turnover and related costs of retraining and also paying any compensation for injured employees.
Indicator	Acceptable Weight, Recommended Weight Limit, Compression limit.
Improvement	Simulation of work process (Carry (Manual Handling Limit) analysis, Lift-Lower (NIOSH) analysis, Biomechanical (Lower Back) analysis)
Result	Reflects the abilities and needs of the worker and leads to more efficient, more productive and safer production or assembly with less work.



Digital Mock-Up for Mechanical products

Aspects of composition of digital mock-up and the requirements of a digital mock-up model.

This makes possible a number of advantages such a:

- Reduce time to market by identifying problems at the design.
- reduce production costs by minimizing the number of prototypes to be made.
- improving product quality by allocating alternative project to be verified before the final one to be elected.
- division of responsibilities regarding product functions within the enterprise.

The DMU of mechanical products, as important engineering data in a company, is supposed to be able to support all the activities in the whole life-cycle of the product including design, manufacture.

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Gherghina

Digital Mock-Up for Mechanical products

Critical points identification	The rapidly increasing product complexity requires the use of functional virtual prototyping.
Indicator	Stresses and strains.
Improvement	Created functional virtual prototyping with simulation.
Result	Digital mock-up design allows engineers to design, to model complex structures and verify the design of a product without ever needing the achieved physically real construction.

MSE



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Gherghina

Spacecraft Collaborative Design Technology

□ A digital mock-up Support collaborative design of spacecraft typical subsystems.

- A digital mock-up of the spacecraft is the assembling of Model-Based Design(MBD) model of all structural components, system equipment and accessories.
- MBD technology is a method to fully express product definition information with integrated three-dimensional entity model.
- In order to meet the requirements of spacecraft design, manufacture, assembly integration and collaborative design of different subsystems.



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Spacecraft Collaborative Design Technology

Typical **applications** of Design-manufacturing integration.



Spacecraft Collaborative Design Technology

MSE

Critical points identification	The information transmission of spacecraft development depends on unstructured information such as documents and drawings, the information of design, manufacturing and assembly are relatively isolated and it is difficult to carry out collaborative design between subsystems
Indicator	Efficiency of collaborative design, assembly efficiency of the spacecraft.
Improvement	Using MBD model as a single data source, building a digital mock-up of spacecraft products.
Result	Compared with traditional serial design, the efficiency of collaborative design is improved by more than 50%. The assembly efficiency of the spacecraft is increased by 30% and shortening the development period of spacecraft .



JING, 2019



Factory critical points identification and suggestions for improvement

Thank You

